

# Trace of the gradient for HJB

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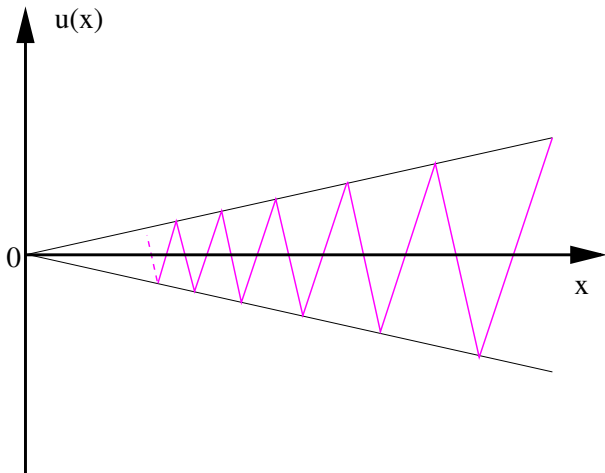
Paris; March 22, 2024

$u$  viscosity solution of HJB  
 $\|Du\|_{L^\infty} \leq C$   
 $C^1$  strictly convex Hamiltonian

}  $\implies$  trace of  $Du$ ?

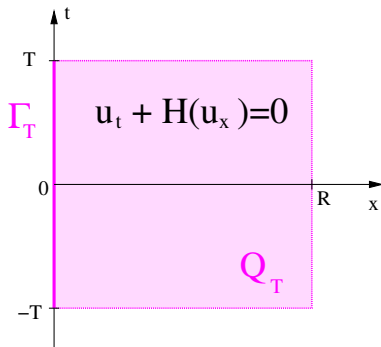
# Case $H \equiv 0$ with no trace of $u_x$

$$u_t + H(u_x) = 0 \quad \text{for } x > 0$$



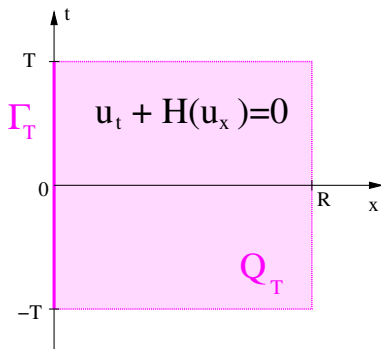
# A model problem

# A model problem in 1D



$u$  Lipschitz up to the boundary  $\Gamma_T$

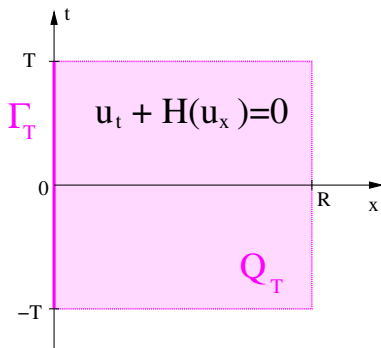
# A model problem in 1D



$H : \mathbb{R} \rightarrow \mathbb{R}$  strictly convex

$$H(\lambda p + (1 - \lambda)q) < \lambda H(p) + (1 - \lambda)H(q) \quad \text{for all } \lambda \in (0, 1), \quad p \neq q$$

# A model problem in 1D



$$\begin{cases} u \text{ Lipschitz up to the boundary } \Gamma_T, \\ H : \mathbb{R} \rightarrow \mathbb{R}, C^1 \text{ strictly convex} \end{cases}$$

Can we define the **trace of  $u_x$**  on  $\Gamma_T$  ?

# A good case on the whole line

$$\begin{cases} u_t + H(u_x) = 0 & \text{for } t > 0, \quad x \in \mathbb{R} \\ H'' \geq 1/K \end{cases}$$

Then  $u$  is semiconcave with

$$u_{xx} \leq \frac{K}{t} \quad (\text{Lax-Oleinik}) \quad \implies \quad u_x \in BV_{t,x}$$

and  $u_x$  has a trace, say for  $x = 0^+$ .

See also

[Cannarsa, Sinestrari, 2004] : semiconcavity estimates

[Bianchini, De Lellis, Robyr, 2011] :  $(u_t, u_x) \in SBV_{t,x}$



# A bad case on the half line

$$\begin{cases} u_t + H(u_x) = 0 & \text{for } t > 0, \quad x > 0 \\ H'' \geq 1/K \end{cases}$$

Then  $|u_x|_{BV_x}$  can blow up in finite time.

[Adimurthi, Ghoshal, Dutta , Veerappa Gowda (2011)]

# A model problem in 1D

$$\left\{ \begin{array}{l} u_t + H(u_x) = 0 \quad \text{on the box } Q_T := (-T, T) \times (0, R) \\ u \text{ Lipschitz up to the boundary } \Gamma_T := (-T, T) \times \{0\} \\ H : \mathbb{R} \rightarrow \mathbb{R}, C^1 \text{ strictly convex} \end{array} \right.$$

Again, can we define the **trace of  $u_x$**  on  $\Gamma_T$  ?

$$\left\{ \begin{array}{l} u_t + H(u_x) = 0 \quad \text{on the box } Q_T := (-T, T) \times (0, R) \\ u \text{ Lipschitz, up to the boundary } \Gamma_T := (-T, T) \times \{0\} \\ H : \mathbb{R} \rightarrow \mathbb{R}, C^1 \text{ strictly convex} \end{array} \right.$$

**Thm TTN (Tangential To Normal), [M.]**

For  $0 = (0, 0) \in \Gamma_T$ ,

$$u_t(0) \text{ exists on } \Gamma_T \quad \implies \quad u_x(0) \text{ exists on } \overline{Q}_T$$

$$\left\{ \begin{array}{l} u_t + H(u_x) = 0 \quad \text{on the box } Q_T := (-T, T) \times (0, R) \\ u \text{ Lipschitz, up to the boundary } \Gamma_T := (-T, T) \times \{0\} \\ H : \mathbb{R} \rightarrow \mathbb{R}, C^1 \text{ strictly convex} \end{array} \right.$$

## Thm TTN (Tangential To Normal), [M.]

For  $0 = (0, 0) \in \Gamma_T$ ,

$$\lambda := u_t(0) \text{ exists on } \Gamma_T \implies u_x(0) \text{ exists on } \overline{Q}_T$$

Precisely

$$u(t, 0) - u(0, 0) = \lambda t + o(|t|) \implies u(X) - u(0) = \hat{D}u(0) \cdot X + o(|X|)$$

for  $X = (t, x)$  and  $\hat{D}u := (u_t, u_x)$ .

$$\left\{ \begin{array}{l} u_t + H(u_x) = 0 \quad \text{on the box} \quad Q_T := (-T, T) \times (0, R) \\ u \text{ Lipschitz on } \overline{Q_T} \\ H : \mathbb{R} \rightarrow \mathbb{R}, C^1 \text{ strictly convex} \end{array} \right.$$

## Thm 2 (Trace of the gradient), [M.]

The gradient  $u_x(t, 0)$  exists for a.e.  $t \in (-T, T)$  and

$$\lim_{\varepsilon \rightarrow 0^+} \int_{Q_T} |u_x(t, \varepsilon x) - u_x(t, 0)| \, dt dx = 0$$

$$\left\{ \begin{array}{l} u_t + H(u_x) = 0 \quad \text{on the box} \quad Q_T := (-T, T) \times (0, R) \\ u \text{ Lipschitz on } \overline{Q_T} \\ H : \mathbb{R} \rightarrow \mathbb{R}, C^1 \text{ strictly convex} \end{array} \right.$$

## Thm 2 (Trace of the gradient), [M.]

The gradient  $u_x(t, 0)$  exists for a.e.  $t \in (-T, T)$  and

$$\lim_{\varepsilon \rightarrow 0^+} \int_{Q_T} |u_x(t, \varepsilon x) - u_x(t, 0)| \, dt dx = 0$$

and more generally

$$\hat{D}u(\cdot, \varepsilon \cdot) \rightarrow (\hat{D}u)|_{\Gamma_T} \quad \text{in} \quad L^1(\text{normal}; L^1(\text{tangential}))$$

(Pointwise to  $L^1$ , using Young measures).

# Application : HJ to CL

If  $u$  is a Lipschitz **viscosity** solution of

$$\begin{cases} u_t + H(u_x) = 0 & \text{for } x > 0 \\ -u_x + v_D = 0 & \text{for } x = 0 \end{cases} \quad (\text{weakly})$$

then  $v := u_x$  is an **entropy** solution of

$$\begin{cases} v_t + H(v)_x = 0 & \text{for } x > 0 \\ v = v_D & \text{for } x = 0 \end{cases} \quad (\text{weakly})$$

See also (when moreover  $H'' \geq \delta > 0$ )

[Cardaliaguet, Forcadel, M., 2023]

[Cardaliaguet, Forcadel, Girard, M., 2023]

[Imbert, Forcadel, M., 2023] : general boundary conditions

For

$$v_t + H(v)_x = 0 \quad \text{for } x > 0$$

Trace of  $v$  on  $\{x = 0\}$  for "nonlinear  $H$ " :

[Vasseur, 2001]

[Panov, 2007]

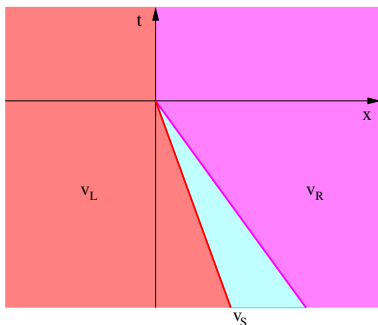


# A counter-example to TTN result, with $H$ not convex

There exists a viscosity solution of  $u_t + H(u_x) = 0$  with  $u(t, 0) \equiv 0$  and

$$v_S < v_R < v_L, \quad C^{1,1}([v_S, v_L]) \ni H = \begin{cases} \text{concave on } [v_S, v_R] \\ \text{convex on } [v_R, v_L] \end{cases}$$

and  $v := u_x$  entropy solution of  $v_t + H(v)_x = 0$



Here  $u(X) - u(0) \neq \hat{D}u(0) \cdot X + o(|X|)$ .

# Higher dimensions and $(t, x)$ -dependence

$$\left\{ \begin{array}{l} u_t + H(Du, X) = 0 \quad \text{on } Q_T := (0, T) \times \Omega \ni (t, x) = X \\ u \text{ Lipschitz on } \bar{Q}_T, \quad H : \mathbb{R}^n \times \bar{Q}_T \rightarrow \mathbb{R} \text{ continuous} \\ H : p \mapsto H(p, X_0), C^1 \text{ strictly convex at some } X_0 \in \Gamma_T := (0, T) \times \partial\Omega \end{array} \right.$$

### Thm TTN' (Tangential To Normal), [M.]

Let

$$\hat{D}u = (u_t, Du)$$

If  $\partial\Omega \in C^1$ , then

$$\hat{D}(u|_{\Gamma_T})(X_0) \text{ exists} \implies \hat{D}u(X_0) \text{ exists}$$

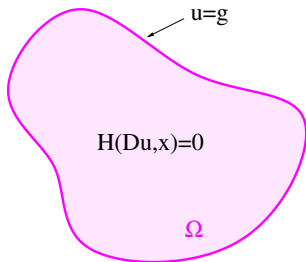
$$\left\{ \begin{array}{l} u_t + H(Du, X) = 0 \quad \text{on } Q_T := (0, T) \times \Omega \ni (t, x) = X \\ \quad \text{with the cylinder } \Omega := B'_1 \times (0, 1) \ni (x', x_n) \\ \\ u \text{ Lipschitz on } \overline{Q}_T, \quad H : \mathbb{R}^n \times \overline{Q}_T \rightarrow \mathbb{R} \text{ continuous} \\ \\ H : p \mapsto H(p, X_0), C^1 \text{ strictly convex at all } X_0 \in \Gamma_T := (0, T) \times B'_1 \times \{0\} \end{array} \right.$$

### Thm 2' (Trace of the gradient), [M.]

Then  $\hat{D}u := (u_t, Du)$  exists a.e. on  $\Gamma_T$  and

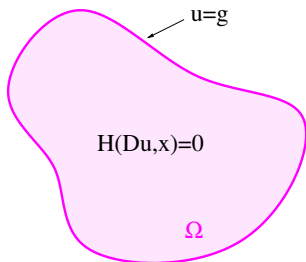
$$\lim_{\varepsilon \rightarrow 0^+} \int_{Q_T} |\hat{D}u(t, x', \varepsilon x_n) - \hat{D}u(t, x', 0)| dt dx' dx_n = 0$$

# Application : Dirichlet problem



$H : p \mapsto H(p, x_0)$ ,  $C^1$  strictly convex for all  $x_0 \in \partial\Omega$

# Application : Dirichlet problem



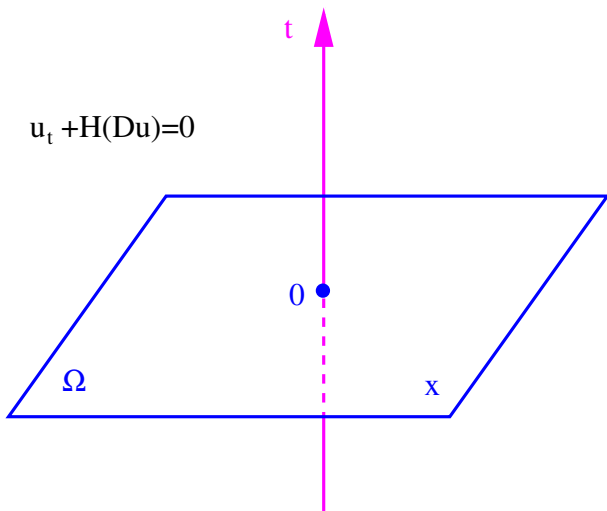
$H : p \mapsto H(p, x_0)$ ,  $C^1$  strictly convex for all  $x_0 \in \partial\Omega$

**Thm TTN\* (Existence of a normal derivative), [M.]**

If  $u$  is Lipschitz on  $\bar{\Omega}$ , and  $\partial\Omega \in C^1$  with  $g \in C^1(\partial\Omega)$ ,  
then  $\frac{\partial u}{\partial n}$  exists everywhere on  $\partial\Omega$ .

# Codimension $d > 1$ and $(t, x)$ -dependence

Codimension  $d > 1$  with  $\Omega := \mathbb{R}^d \setminus \{0\}$



Similar to  
[Achdou, Le Bris, 2023]



Codimension  $d > 1$  with  $\Omega := \mathbb{R}^d \setminus \{0\}$

$$\left\{ \begin{array}{l} u_t + H(Du) = 0 \quad \text{on} \quad Q_T := (-T, T) \times \Omega, \quad \Omega := \mathbb{R}^d \setminus \{0\} \\ \quad \quad \quad \text{with} \quad \Gamma_T := (-T, T) \times \{0\} \\ \\ u \text{ Lipschitz on } \overline{Q}_T, \quad H : \mathbb{R}^d \rightarrow \mathbb{R}, C^1 \text{ strictly convex} \end{array} \right.$$

### Thm TTN'' (Tangential To Normal), [M.]

For  $0 = (0, 0) \in \Gamma_T$  and  $\hat{D}u = (u_t, Du)$ , we have

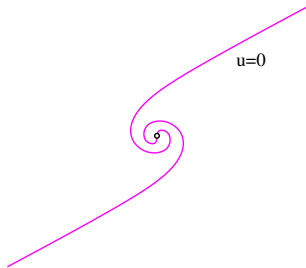
$\hat{D}(u|_{\Gamma_T})(0)$  exists along  $\Gamma_T \implies u$  has **all direct. deriv.** at 0 along  $\overline{Q}_T$

$$\frac{u(\varepsilon X) - u(0)}{\varepsilon} =: u^\varepsilon(X) \rightarrow u^0(X) \quad \text{with} \quad u^0(\lambda X) = \lambda u^0(X), \quad \lambda > 0$$

# A counter-example with $H(p, x)$ not Hölder in $x$

For  $\partial_t = 0$ ,  $d = 2$ , there exists a viscosity solution  $u$  of

$$\begin{cases} a(x)|Du|^2 = 1 & \text{on } B_1 \subset \mathbb{R}^2 \\ 1 \leq a \leq 2, & \text{with } a \text{ only continuous on } B_1 \end{cases}$$



and

$$\frac{u(\varepsilon x) - u(0)}{\varepsilon} =: u^\varepsilon(x) \quad \text{does not converges as } \varepsilon \rightarrow 0$$

# Codimension $d > 1$ , Hölder coefficients

$$\left\{ \begin{array}{l} u_t + H(Du, X) = 0 \quad \text{on} \quad Q_T := (-T, T) \times B'_1 \times \Omega, \quad B'_1 \subset \mathbb{R}^m \\ \Omega := B_1 \setminus \{0\} \subset \mathbb{R}^d \quad \text{with} \quad \Gamma_T := (-T, T) \times B'_1 \times \{0\} \\ u \text{ Lipschitz on } \overline{Q}_T, \quad H : \mathbb{R}^{m+d} \times \overline{Q}_T \rightarrow \mathbb{R} \text{ continuous} \end{array} \right.$$

$$\left. \begin{array}{l} 0 < \delta \leq D_{pp}^2 H \leq \delta^{-1} \\ H \text{ } \alpha\text{-Hölder in } X \text{ for bounded } p \end{array} \right\} \text{ for all } X \text{ in a neighborhood of } 0$$

## Thm TTN''' (Tangential To Normal), [M.]

For  $0 = (0, 0, 0) \in \Gamma_T$  and  $\hat{D}u = (u_t, Du)$ , we have

$\hat{D}(u|_{\Gamma_T})(0)$  exists along  $\Gamma_T \implies u$  has **all direct. deriv.** at 0 along  $\overline{Q}_T$

$$\frac{u(\varepsilon X) - u(0)}{\varepsilon} =: u^\varepsilon(X) \rightarrow u^0(X) \quad \text{with} \quad u^0(\lambda X) = \lambda u^0(X), \quad \lambda > 0$$

same assumptions

$$\left. \begin{array}{l} 0 < \delta \leq D_{pp}^2 H \leq \delta^{-1} \\ H \text{ } \alpha\text{-Hölder in } X \text{ for bounded } p \end{array} \right\} \text{ for all } X \text{ in a } \underline{\text{neighborhood}} \text{ of } \Gamma_T$$

### Thm 2''' (Trace of directional derivatives), [M.]

Let  $\hat{D}u = (u_t, Du)$ . Then a.e. on  $\Gamma_T$  and for any  $\xi \in \mathbb{R}^{1+m+d}$ , the quantity  $\xi \cdot \hat{D}u$  exists and

$$\lim_{\varepsilon \rightarrow 0^+} \int_{Q_T} |\xi \cdot \hat{D}u(t, x', \varepsilon x) - \xi \cdot \hat{D}u(t, x', 0)| dt dx' dx = 0$$

# Arguments for TTN

# A Liouville-type result

$$\begin{cases} u_t + H(Du) = 0 & \text{on } Q = \mathbb{R} \times \mathbb{R}^m \times \Omega, \\ u = 0 & \text{on } \Gamma := \mathbb{R} \times \mathbb{R}^m \times \{0\} \end{cases}$$

with

$$\Omega := \begin{cases} \mathbb{R}^d \setminus \{0\} & \text{if } d \geq 2 \\ (0, +\infty) & \text{if } d = 1 \end{cases}$$

## Thm 4 (Liouville-type result), [M.]

Let  $H : \mathbb{R}^{m+d} \rightarrow \mathbb{R}$  be  $C^1$  strictly convex and **superlinear**. If  $u$  is a viscosity solution and  $\|(u_t, Du)\|_{L^\infty(\bar{Q})} < +\infty$ , then

$$u(t, x', x) = u(0, 0, x) \quad \text{for all } (t, x', x) \in \mathbb{R} \times \mathbb{R}^m \times \bar{\Omega}$$

# Consequence for the first blow-up

If

$$\begin{cases} u_t + H(Du, X) = 0 & \text{on } Q_T, \\ u = 0 & \text{on } \Gamma_T \ni 0 \end{cases}$$

then

$$\frac{u(\varepsilon X) - u(0)}{\varepsilon} =: u^\varepsilon(X) \rightarrow u^0(X)$$

where the blow-up limit  $u^0$  is a global solution of

$$\begin{cases} u_t^0 + H(Du^0, 0) = 0 & \text{on } Q = \mathbb{R} \times \mathbb{R}^m \times \Omega, \\ u^0 = 0 & \text{on } \Gamma := \mathbb{R} \times \mathbb{R}^m \times \{0\} \end{cases}$$

# Case $m = 0$ , codimension $d = 1$ , without $X$

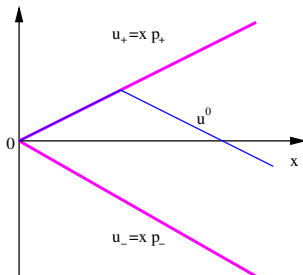
$$\begin{cases} u_t^0 + H(u_x^0) = 0 & \text{on } Q := \mathbb{R} \times (0, +\infty), \\ u^0 = 0 & \text{on } \Gamma := \mathbb{R} \times \{0\} \end{cases}$$

Then

$$\text{Liouville} \implies u^0(t, x) = u^0(x)$$

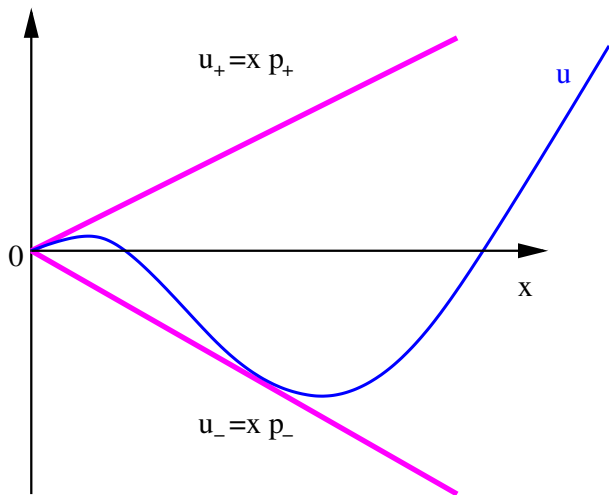
and

$$u^0(x) = \min(xp_+, c + xp_-) \quad \text{with} \quad H(p_{\pm}) = 0, \quad p_- \leq p_+$$

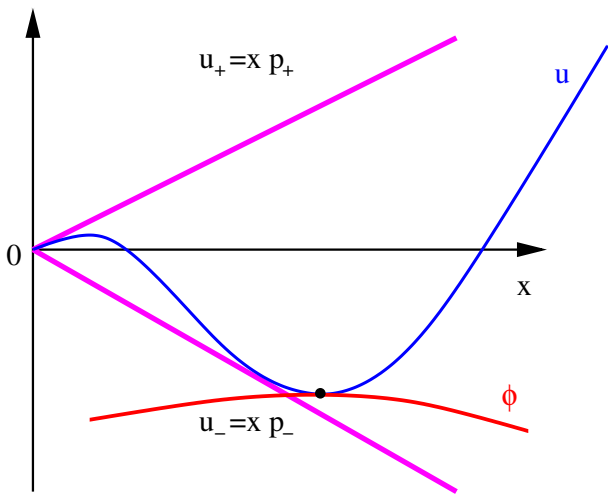




# Exclusion of oscillations of $u$ between $u_-$ and $u_+$



# Exclusion of oscillations of $u$ between $u_-$ and $u_+$



$$0 + H(\phi_x) \geq 0 \quad \text{contradiction with} \quad \begin{cases} p_- < 0 < p_+ \\ H(p_{\pm}) = 0 > H(0) \end{cases}$$

Uniqueness of the limit  $u^\varepsilon \rightarrow u^0 \in \{u_-, u_+\}$

Hence

$$\frac{u(\varepsilon X) - u(0)}{\varepsilon} \rightarrow u^0(x) = px \quad \text{with} \quad p = p_\pm$$

Uniqueness of the limit  $u^\varepsilon \rightarrow u^0 \in \{u_-, u_+\}$

Hence

$$\frac{u(\varepsilon X) - u(0)}{\varepsilon} \rightarrow u^0(x) = px \quad \text{with} \quad p = p_\pm$$

i.e.

$$u(X) = u(0) + px + o(|X|) \quad \text{where} \quad X = (t, x)$$

Hence

$$\hat{D}u = (u_t, u_x) \quad \text{exists at} \quad X = (0, 0) = 0$$

# Arguments for Liouville result

## Step 1 : barriers $u_{\pm}$

$$\begin{cases} u_t + H(Du) = 0 & \text{on } Q = \mathbb{R} \times (0, +\infty), \\ u = 0 & \text{on } \Gamma = \mathbb{R} \times \{0\} \end{cases}$$

with

$$\|(u_t, u_x)\|_{L^\infty(\bar{Q})} < +\infty$$

By comparison, we show

$$u_-(x) \leq u(t, x) \leq u_+(x), \quad u_{\pm}(x) = xp_{\pm}$$

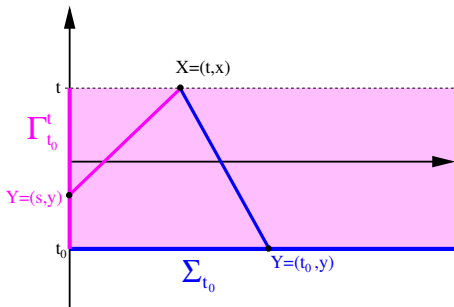
Define the characteristic velocities

$$\xi_{\pm} := DH(p_{\pm}) \implies \xi_- < 0 < \xi_+$$

## Step 2 : Representation formula

For  $t_0 < t$  and  $x > 0$ , we have

$$u(X) := \min(u_{\Gamma_{t_0}^t}, u_{\Sigma_{t_0}})(X)$$



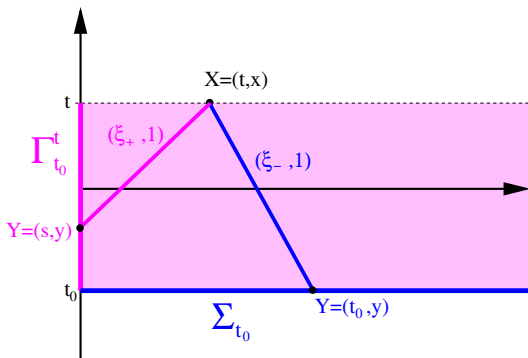
with  $X = (t, x)$ ,  $Y = (s, y)$  and

$$u_A(X) := \inf_{Y \in A} \left\{ u(Y) + \int_s^t \mathcal{L} \left( \frac{x-y}{t-s} \right) d\tau \right\} \quad \text{with} \quad \mathcal{L} := H^*$$

## Step 3 : Rigidity of optimal trajectories

For  $t_0 < t$  and  $x > 0$ , we have

$$u(X) := \min(u_{\Gamma_{t_0}^t}, u_{\Sigma_{t_0}})(X)$$



with

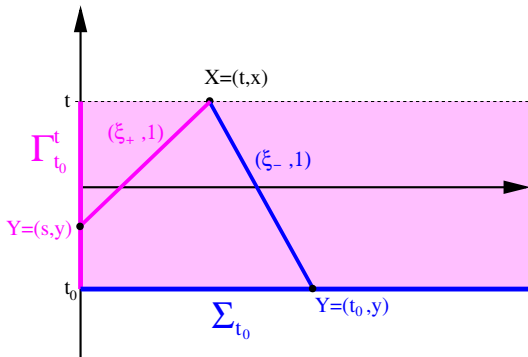
$\xi_-, \xi_+$  selected by the barriers  $u_-, u_+$



## Step 3 : Rigidity of optimal trajectories

For  $t_0 < t$  and  $x > 0$ , we have

$$u(X) := \min(u_{\Gamma_{t_0}^t}, u_{\Sigma_{t_0}})(X)$$



This forces

$$u_{\Gamma_{t_0}^t}(X) = u_+(x), \quad u_{\Sigma_{t_0}}(X) = c + u_-(x) \quad \text{for} \quad \frac{t - t_0}{x} \gg 1$$

# Comments on the general case

Codimension  $d > 1$  is much more delicate.

$X$ -dependence :

need to control  $\xi_-(X)$  which can rotate.

$$u_t + H(Du) = 0 \quad \text{in} \quad \{x_n > 0\} \quad (1)$$

## Trace conjecture

Let  $u$  be a Lipschitz viscosity solution of (1).

If the graph of  $H$  does not contain any nondegenerate segments, then  $(u_t, Du)$  has a trace on  $\{x_n = 0\}$ .

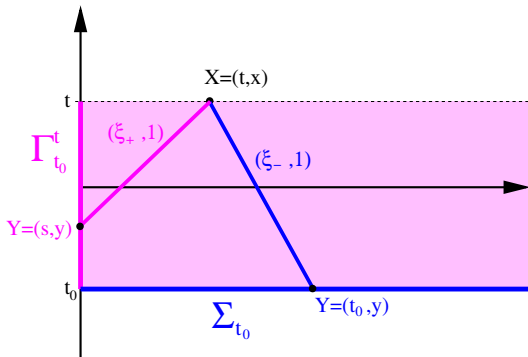
THANKS!

# The End

## Step 3 : Rigidity of optimal trajectories

For  $t_0 < t$  and  $x > 0$ , we have

$$u(X) := \min(u_{\Gamma_{t_0}^t}, u_{\Sigma_{t_0}})(X)$$



with

$$u_{\Gamma_{t_0}^t}(X) = u_+(x), \quad u_{\Sigma_{t_0}}(X) = c + u_-(x) \quad \text{for} \quad \frac{t - t_0}{x} \gg 1$$

## Step 3 : Explanation

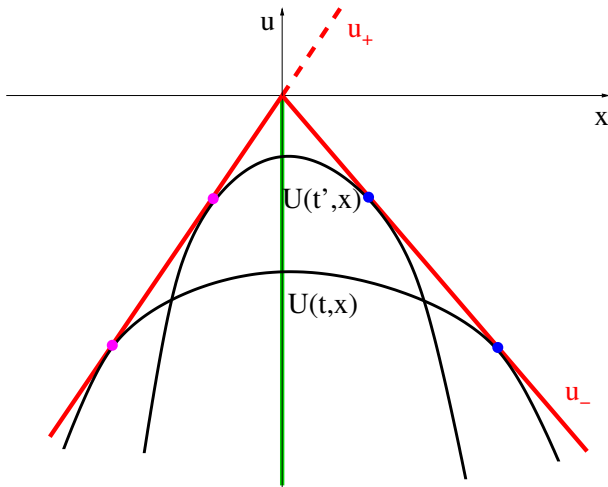
For  $\mathcal{L} = H^*$ ,

$$U(t, x) := \begin{cases} t\mathcal{L}\left(\frac{x}{t}\right) & \text{for } (t, x) \in (-\infty, 0) \times \mathbb{R} \\ 0 & \text{for } t = 0, \quad x = 0 \\ -\infty & \text{for } t = 0, \quad x \neq 0 \end{cases}$$

is a fundamental solution of

$$u_t + H(Du) = 0 \quad \text{on} \quad (-\infty, 0) \times \mathbb{R}$$

### Step 3 : $U$ tangential to $u_{\pm}$



with

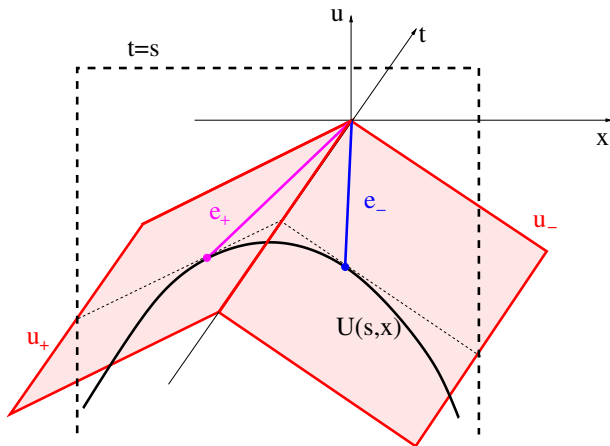
$$t < t' < 0$$



# Step 3 : $U$ tangential to $u_{\pm}$

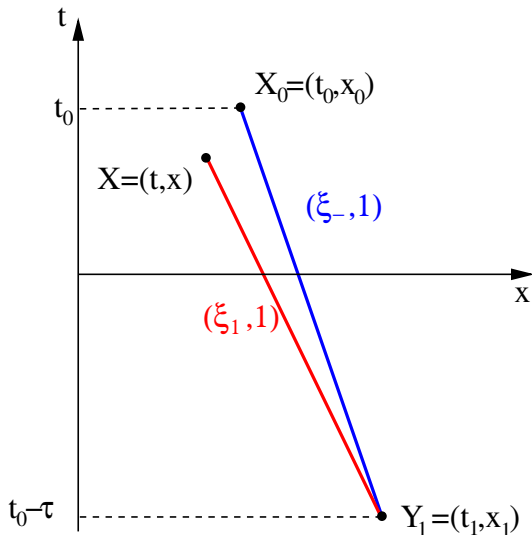
characteristic vectors

$$e_+ = (\xi_+, 1, \mathcal{L}(\xi_+)) \quad \text{and} \quad e_- = (\xi_-, 1, \mathcal{L}(\xi_-))$$



## Step 4 : consequence of rigidity in $\xi_-$

If  $u(X_0) < u_+(x_0)$ , then  $u(X_0) = u(Y_1) + \tau \mathcal{L}(\xi_-)$ .



with  $\tau \gg 1$ .

## Step 4 : consequence of rigidity in $\xi_-$

For  $X = (t, x)$ , we have

$$\begin{aligned} & u(X) - u(X_0) \\ \leq & -u(X_0) + u(Y_1) + (t - t_1)\mathcal{L}(\xi_1) && \text{with } \xi_1 := \frac{x - y_1}{t - t_1} \\ = & (t - t_0)\mathcal{L}(\xi_1) + \tau \{ \mathcal{L}(\xi_1) - \mathcal{L}(\xi_-) \} && \text{with } t - t_1 = (t - t_0) + \tau \\ = & (t - t_0)\mathcal{L}(\xi_1) + \tau \int_0^1 d\sigma \bar{\xi} \cdot D\mathcal{L}(\xi_- + \sigma\bar{\xi}) \end{aligned}$$

and

$$\bar{\xi} := \xi_1 - \xi_- = \tau^{-1}A + o(\tau^{-1}) \quad \text{with} \quad A := x - x_0 - (t - t_0)\xi_-$$

## Step 4 : consequence of rigidity in $\xi_-$

As  $\tau \rightarrow +\infty$ , we get

$$u(X) - u(X_0) \leq (p_-) \cdot (x - x_0)$$

By symmetry  $X \leftrightarrow X_0$ , we get in  $\{u < u_+\}$

$$u(t, x) - u(t_0, x_0) = (p_-) \cdot (x - x_0)$$

i.e.

$$u(t, x) = c + u_-(x) \quad \text{in} \quad \{u < u_+\}$$