

**De  $\mathcal{P}_2(\mathbb{R}^d)$  à  $L^2_{\mathbb{P}}(\Omega, \mathbb{R}^d)$ :**  
**deux points de vue sur un problème de contrôle**  
**et son équation de HJB.**  
*2 paires de lunettes...*

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Antonio Marigonda (Verona), Marc Quincampoix (Brest)

# Plan

- 1 The Wasserstein Space
- 2 A multi-agent optimal control problem
- 3 Hamilton-Jacobi in the space of Wasserstein
- 4 Extending the Hamiltonian in  $L^2_{\mathbb{P}}$  in a regular way

## The Wasserstein space

$$\mathcal{P}_2(\mathbb{R}^d) := \left\{ \mu \in \mathcal{P}(\mathbb{R}^d) : \int_{\mathbb{R}^d} |x|^2 d\mu(x) < +\infty \right\}$$

## The Wasserstein Distance

For  $\mu, \nu \in \mathcal{P}_2(\mathbb{R}^d)$ :

$$\Pi(\mu, \nu) = \{ \gamma \in \mathcal{P}_2(\mathbb{R}^{2d}) : \gamma \text{ has marginals } \mu \text{ and } \nu \}$$

$$W_2(\mu, \nu) = \min_{\gamma \in \Pi(\mu, \nu)} \left\{ \left( \int_{\mathbb{R}^{2d}} |y - x|^2 d\gamma(x, y) \right)^{1/2} \right\}$$

## Probability space

- $(\Omega, \mathcal{B}(\Omega), \mathbb{P}) = ([0, 1], \mathcal{B}([0, 1]), \mathcal{L}^1_{[0,1]})$

## Probability measures as laws

- For all  $\mu \in \mathcal{P}_2(\mathbb{R}^d)$  it exists  $X \in L^2_{\mathbb{P}}(\Omega, \mathbb{R}^d)$  such that:

$$\mu = X\#\mathbb{P}, \quad \mathbb{P}_X = \mu, \quad \text{the law of } X \text{ is } \mu$$

the image measure of  $\mathbb{P}$  by  $X$  is  $\mu$ :  $\mu(A) = \mathbb{P}(X^{-1}(A))$ .

- For all  $\gamma \in \Pi(\mu, \nu)$ , it exists  $X, Y \in L^2_{\mathbb{P}}(\Omega, \mathbb{R}^d)$  such that:

$$\gamma = (X, Y)\#\mathbb{P}, \quad X\#\mathbb{P} = \mu, \quad Y\#\mathbb{P} = \nu.$$

# Through Hilbertian glasses

## Wasserstein space

$$W_2(\mu, \nu) = \min \left\{ \|X - Y\|_{L^2_{\mathbb{P}}} : X_{\#}\mathbb{P} = \mu, Y_{\#}\mathbb{P} = \nu \right\}.$$

## $\mathcal{P}_2(\mathbb{R}^d)$ as a quotient

- $X \sim X'$  iff  $X_{\#}\mathbb{P} = X'_{\#}\mathbb{P}$
- $\mathcal{P}_2(\mathbb{R}^d) \equiv L^2_{\mathbb{P}}(\Omega) / \sim$

# Transport maps

## Transport plans supported on graphs

$$\gamma = (\text{Id}, T)\#\mu, \quad \mu \in \mathcal{P}_2(\mathbb{R}^d), \quad T \in L^2_{\mu}(\mathbb{R}^d, \mathbb{R}^d)$$

$$\int \varphi(x, y) d\gamma(x, y) = \int \varphi(x, Tx) d\mu(x).$$

## Transport plans supported on graphs

$$\gamma = (X, T \circ X)\#\mathbb{P}, \quad X \in L^2_{\mathbb{P}}(\Omega, \mathbb{R}^d), \quad T \in L^2_{X\#\mathbb{P}}(\mathbb{R}^d, \mathbb{R}^d),$$

$$\int \varphi(x, y) d\gamma(x, y) = \int \varphi(X, T \circ X) d\mathbb{P}.$$

# Maps and lifts

## Lifts and rearrangement invariance

- Let  $u : \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R}$  we define the **lift** of  $u$  as:

$$U : X \in L^2_{\mathbb{P}}(\Omega, \mathbb{R}^d) \mapsto u(X\sharp\mathbb{P}) \in \mathbb{R}.$$

- Then  $U : L^2_{\mathbb{P}}(\Omega, \mathbb{R}^d) \rightarrow \mathbb{R}$  is **rearrangement invariant**:

$$X\sharp\mathbb{P} = Y\sharp\mathbb{P} \Rightarrow U(X) = U(Y).$$

- $u$  is continuous /  $W_2$  **iff** its lift  $U$  is continuous /  $\|\cdot\|_{L^2_{\mathbb{P}}}$ .

# Plan

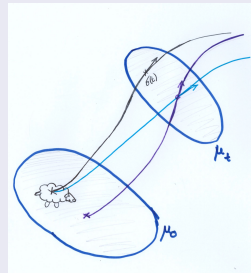
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# Controlled trajectories: a toy example

## A toy example: controlling the trajectory of a herd of sheep

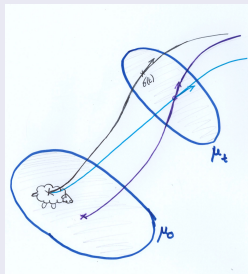
- $\eta \in \mathcal{P}(\mathcal{C}([t_0, T], \mathbb{R}^d))$
- $e_t(\sigma) = \sigma(t)$ ,  $\mu_t := e_t\# \eta = \eta \circ e_t^{-1}$ ,
- $\eta$  concentrated on curves  $\sigma$  with:  
 $\dot{\sigma}(t) = f(\sigma(t), \underline{u}(t, \sigma), \mu_t)$  a.e.  $t$
- $f$  is regular, affine on  $\underline{u}$
- $\eta = \eta^{t,x} \otimes \mu_t(x)$



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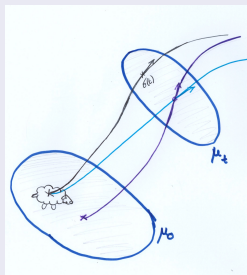
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## Controlled trajectories: a toy example

### Some computations with hands

- $\mu_t := \mathbf{e}_t \# \eta$ ,  $\eta = \eta^{t,x} \otimes \mu_t(x)$   
Dynamic:  $\dot{\sigma}(t) = f(\sigma(t), \underline{u}(t, \sigma), \mu_t)$
- We integrate the dynamic with respect to  $\eta^{t,x}$ :

$$\begin{aligned} v_t(x) &:= \int \dot{\sigma}(t) d\eta^{t,x}(\sigma) = \int f(\sigma(t), \underline{u}(t, \sigma), \mu_t) d\eta^{t,x}(\sigma) \\ &= f\left(x, \int \underline{u}(t, \sigma) d\eta^{t,x}(\sigma), \mu_t\right) \mu_t\text{-a.e.} \end{aligned}$$

## Controlled trajectories: a toy example

Dynamic in the space of Wasserstein

$$v_t(x) = f(x, \underline{w}(t, x), \mu_t) \quad \mu_t\text{-a.e.}$$

Where  $\underline{w}$  is a control.

Trajectories in  $AC^2([t_0, T], \mathcal{P}_2(\mathbb{R}^d))$  (Ambrosio, Gigli, Savaré)

We assume  $t \mapsto \mu_t \in \mathcal{P}_2(\mathbb{R}^d)$  is in  $AC^2([t_0, T], \mathcal{P}_2(\mathbb{R}^d))$ ,

$$\int_0^T \int_{\mathbb{R}^d} |v_t(x)|^2 d\mu_t(x) dt < +\infty$$

$$\partial_t \mu_t + \operatorname{div}(v_t \mu_t) = 0 \text{ in } \mathbb{R}^d \times ]t_0, T[$$

# Be careful

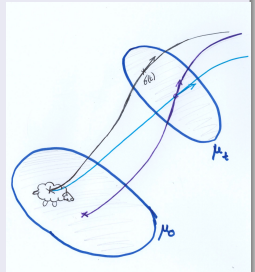
## Remark

Define a plan  $\gamma_t$ :

$$\int \varphi d\gamma_t(x, z) = \int \varphi(\sigma(t), \dot{\sigma}(t)) d\eta^{t,x}(\sigma)$$

$\gamma_t$  may not be of the type  $(Id, v_t)\# \mu_t$

$\gamma_t$  may not be supported on a graph!



## A control problem

The Value function (Marigonda, Quincampoix, J. Marigonda, Quincampoix)

$$\mathcal{V}(t_0, \mu_0) := \inf_{(v_t, \mu_t), \underline{w}} \{ \mathcal{G}(\mu_T) : \mu_{t_0} = \mu_0 \}$$

admissible curves are in  $AC^2([t_0, T], \mathcal{P}_2(\mathbb{R}^d))$  with

$$v_t(x) = f(x, \underline{w}(t, x), \mu_t) \quad \mu_t\text{-a.e.}$$

Assume for simplicity that  $\mathcal{G}$  is Lipschitz so that  $\mathcal{V}$  is regular.

How can we express this problem in  $L^2_{\mathbb{P}}$ ?

Cavagnari, Lisini, Orrieri, Savaré,  
J. Marigonda, Quincampoix and J.

## How can we express this problem in $L^2_{\mathbb{P}}$ ?

A fonctionnal in  $L^2_{\mathbb{P}}$  candidate to be the lift of  $\mathcal{V}$

$$W(t_0, X) = \inf_{(X_t, \underline{u})} \left\{ \mathcal{G}(X_T \# \mathbb{P}) : X_{t_0} = X \right\}$$

admissible curves are in  $AC^2([t_0, T], L^2_{\mathbb{P}}(\Omega)^d)$  with

$$\dot{X}_t(\omega) = f(X_t(\omega), \underline{u}(t, \omega), X_t \# \mathbb{P})$$

$W$  is regular. Do we have that  $W(\cdot, X) = \mathcal{V}(\cdot, \mu_0)$  if  $X \# \mathbb{P} = \mu_0$ ?

### Question

Given an admissible  $\mu_t$ , can we find  $X_t$  admissible for  $W$  such that:

$$X_t \# \mathbb{P} = \mu_t?$$



# From Wasserstein to $L^2_{\mathbb{P}}$

## Building $X_t$

- The **Superposition Principle (AGS)** gives  $\eta \in \mathcal{P}(\mathcal{C}([t_0, T], \mathbb{R}^d))$  associated to  $\mu_t: e_t \# \eta = \mu_t$
- It exists  $T_\eta \in L^2_{\mathbb{P}}(\Omega, \mathcal{P}(\mathcal{C}([t_0, T], \mathbb{R}^d)))$  such that:

$$T_\eta \# \mathbb{P} = \eta.$$

- set  $X_t := (e_t \circ T_\eta)$  so that:

$$X_t \# \mathbb{P} = (e_t \circ T_\eta) \# \mathbb{P} = e_t \# \eta = \mu_t$$

$$\dot{X}_t(\omega) = v_t(X_t(\omega)) = f(X_t(\omega), \underline{u}(t, \omega), X_t \# \mathbb{P})$$

with  $\underline{u}(t, \omega) := \underline{w}(t, X_t(\omega))$ .

# From Wasserstein to $L^2_{\mathbb{P}}$

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**Concentrated on curves such that  $\dot{\sigma} = v_t(\sigma)$**
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## Value in $L^2_{\mathbb{P}}$

### Consequence on the value

$$\mathcal{V}(t_0, \mu_0) \geq W(t_0, X_{t_0})$$

### Problem

We cannot choose the starting point  $X_{t_0}$  among all  $Y_0$  such that  $Y_0 \# \mathbb{P} = \mu_0$

## Solving problem

### Important tool

Let  $X, Y \in L^2_{\mathbb{P}}(\Omega, \mathbb{R}^d)$  such that  $X\# \mathbb{P} = Y\# \mathbb{P}$ .

Then, for any  $n > 0$ , there exists  $\tau_n : \Omega \rightarrow \Omega$  bijective s.t.:

- (i)  $\|X \circ \tau_n - Y\|_{L^\infty(\Omega, \mathbb{R}^d)} \leq \frac{1}{n}$ ,
- (ii)  $\tau_n\# \mathbb{P} = \tau_n^{-1}\# \mathbb{P} = \mathbb{P}$ .

Of course  $(X \circ \tau_n)\# \mathbb{P} = X\# \mathbb{P}$ .

## Solving the problem

Solving the problem: We cannot choose  $X_{t_0}$

- Given  $Y_0$  such that  $Y_0 \# \mathbb{P} = \mu_0$  and  $X_t$  as above
- Using the tool, build  $Y_t^n = X_t \circ \tau_n$  with:

$$(X_t \circ \tau_n) \# \mathbb{P} = \mu_t, \quad \|Y_0 - Y_{t_0}^n\| \leq \frac{1}{n}.$$

- $W(\cdot, Y_{t_0}^n) \leq \mathcal{V}(\cdot, \mu_0)$
- (!) the sequence of curves may not converge
- we don't care because of the regularity of  $W$ .

## Consequence

$$\mathcal{V}(\cdot, \mu_0) \geq W(\cdot, Y_0) \quad \text{if } Y_0 \# \mathbb{P} = \mu_0.$$

# From $L^2_{\mathbb{P}}$ to Wasserstein: The opposite inequality

## From $L^2_{\mathbb{P}}$ to Wasserstein

- Let  $Y_t$  such that:

$$\dot{Y}_t(\omega) = f(Y_t(\omega), \underline{u}(t, \omega), Y_t \# \mathbb{P}).$$

- Set  $\mu_t := Y_t \# \mathbb{P}$  and  $\gamma_t = (Y_t, \dot{Y}_t) \# \mathbb{P}$
- $v_t(x) = \int y d\gamma_t^x(y)$  is the projection of  $\dot{Y}_t$  on

$$H_{Y_t} = \{\varphi \circ Y_t : \varphi \in L^2_{Y_t \# \mathbb{P}}\}.$$

- Note that  $\gamma_t$  may divide masses.
- $t \mapsto \mu_t$  is admissible for  $\mathcal{V}(Y_{t_0} \# \mathbb{P})$

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- $v_t(x) = \int y d\gamma_t^x(y)$ ,  $v_t \circ X_t$  is the projection of  $\dot{Y}_t$  on

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# Equality of problems in Wasserstein and $L^2_{\mathbb{P}}$

## Equality of values: $W$ is the lift of $\mathcal{V}$

$$\mathcal{V}(t_0, \mu_0) = \inf_{\mu_{t_0} = \mu_0} \mathcal{G}(\mu_T)$$

$$(\mu_s)_s \in AC^2([t_0, T], \mathcal{P}_2(\mathbb{R}^d))$$

$$v_t(x) = f(x, \underline{w}(t, x), \mu_t)$$

$$V(t_0, X) = \inf_{X_{t_0} = X} \mathcal{G}(X_T \# \mathbb{P})$$

$$(X_t)_t \in AC^2([t_0, T], L^2_{\mathbb{P}}(\Omega)^d)$$

$$\dot{X}_t(\omega) = f(X_t, \underline{u}(t, \omega), X_t \# \mathbb{P})$$

## Remarks

The problem in  $L^2_{\mathbb{P}}$  may have no solution, it depends on the choice of  $X$ .

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## A result in Wasserstein space

Characterization of the value (Marigonda Quincampoix, J.  
Marigonda Quincampoix, J.)

The functional  $\mathcal{V}$  is the unique **viscosity solution** of :

$$(HJ) \begin{cases} \partial_t u(t, \mu) + \mathcal{H}(\mu, D_\mu u(t, \mu)) = 0 & \forall (t, \mu) \in [0, T] \times \mathcal{P}_2(\mathbb{R}^d) \\ u(T, \mu) = \mathcal{G}(\mu) & \forall \mu \in \mathcal{P}_2(\mathbb{R}^d) \end{cases}$$

with  $\mathcal{H}$  defined for  $(\mu, p) \in \mathcal{P}_2 \times L^2_\mu$  as:

$$\mathcal{H}(\mu, p) := \inf_{\underline{u}} \left\{ \int_{\mathbb{R}^d} f(x, \underline{u}(x), \mu) \cdot p(x) d\mu(x) \right\}.$$

# Fréchet Subdifferential in Wasserstein

## Subdifferential (Gangbo, Nguyen and Tudorascu)

Let  $(t_0, \mu_0) \in [0, T[ \times \mathcal{P}_2(\mathbb{R}^d)$ , we have  $(p_t, p_\mu) \in D^- u(t_0, \mu_0)$  if:

- $p_\mu \in \mathcal{T}_{\mu_0}(\mathbb{R}^d)$
- for all  $(t, \nu), \gamma \in \Pi(\mu_0, \nu)$  :

$$u(t, \nu) \geq u(t_0, \mu_0) + p_t(t - t_0) + \int p_\mu(x) \cdot (y - x) d\gamma(x, y) \\ + o\left(\sqrt{\|x - y\|_{L^2_\gamma}^2 + |t - t_0|^2}\right).$$

## Viscosity solution

### Definition (Gangbo, Nguyen and Tudorascu)

- $w$  is a **viscosity supersolution** of (HJ) if for all  $(t_0, \mu_0) \in [0, T] \times \mathcal{P}_2(\mathbb{R}^d)$ :

$$p_t + \mathcal{H}(\mu_0, p_\mu) \leq 0 \quad \forall (p_t, p_\mu) \in D^- w(t_0, \mu_0).$$

- define **subsolutions** in the same way.
- $w$  is a **viscosity solution** if it is both a supersolution and a subsolution.

# Translating the notion of viscosity solution in $L^2_{\mathbb{P}}$

## Lift of $\mathcal{H}$

We set  $H(X, p \circ X) := \mathcal{H}(X \# \mathbb{P}, p)$  for all  $p \in L^2_{X \# \mathbb{P}}(\mathbb{R}^d, \mathbb{R}^d)$ .

## Fréchet sub-differential in $L^2_{\mathbb{P}}$

$(p_t, Z) \in D^- U(t_0, X)$  if for all  $(t, Y)$ , it holds:

$$U(t, Y) \geq U(t_0, X) + p_t(t - t_0) + \langle Z, Y - X \rangle \\ + o\left(\sqrt{\|Y - X\|_{L^2_{\mathbb{P}}}^2 + |t - t_0|^2}\right)$$

## Viscosity supersolution in Wasserstein space

$\mathcal{V}$  is a **supersolution** in the previous sense if

$$p_t + H(X, p_X \circ X) \leq 0 \quad \forall (p_t, p_X \circ X) \in D^- V(t, X)$$

with  $p_X \in \mathcal{T}_{X\#\mathbb{P}}(\mathbb{R}^d)$ .

## Crucial points

- The lift of  $\mathcal{H}$  is not defined on all  $(L^2_{\mathbb{P}}(\mathbb{R}^d, \mathbb{R}^d))^2$ ,
- The definition of  $\mathcal{P}_2$ -viscosity super-solution involves only a part of the Fréchet subdifferential in  $L^2_{\mathbb{P}}$
- $U$  is a viscosity solution in  $L^2_{\mathbb{P}} \Rightarrow u$  is a viscosity solution in Gangbo-Nguyen-Tudorascu sense.
- If we want  $V$  to be a viscosity solution in  $L^2_{\mathbb{P}}$ , we have to **extend** the lift  $H$ .

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## Example

### Lions' lecture at the Collège de France

- He considers  $\mathcal{H}(\mu, \rho) = \|\rho\|_{L^2_{\mu}}^2$
- its Lift is  $H(X, \rho \circ X) = \|\rho \circ X\|_{L^2_{\mathbb{P}}}^2$
- which he naturally extends as

$$\tilde{H}(X, Y) = \|Y\|_{L^2_{\mathbb{P}}}^2$$

- this extension is regular.

We would like to do that in more general cases.

# Literature

## Literature

Several extensions already exist in the literature

- **Gangbo and Tudorascu:**  $H_1(X, Z)$
- **Cavagnari, Marigonda, Quincampoix:**  $H_2(X, Z)$ .
- In both cases a projection of  $Z$  in  $H_X$  is used in order to turn  $(X, Z)$  into some  $(X, p \circ X)$ .
- In other terms they turn  $\gamma(x, z) = (X, Z) \# \mathbb{P}$  into a plan supported on the graph of  $x \mapsto \int z d\gamma^x$ .
- They turn "**transport plans into transport plan supported on graphs**".

## Properties of these extensions

### Theorem (Gangbo, Tudorascu)

$u$  is a **viscosity solution** in  $\mathcal{P}_2(\mathbb{R}^d)$  in the sense of Gangbo, Nguyen, Tudorascu iff **its lift**  $U$  is a **viscosity solution** in  $L^2_{\mathbb{P}}$  of the corresponding equation with  $H_1$ .

### Problems

- Even if  $\mathcal{H}$  is quite nice,  $H_1(X, Z)$  and  $H_2(X, Z)$  **are not continuous** on  $(X, Z)$ .
- This comes from the fact that: **transport plans can be approximated by transport plans supported on graphs.**
- The lack of continuity prevents using classical results of Crandall and Lions.

# Subdifferential in $[t_0, T] \times L^2_{\mathbb{P}}$

## Fréchet Subdifferential

$(p_t, Z) \in D^- U(t_0, X)$  if  $\forall (t, Y)$ :

$$U(t, Y) \geq U(t_0, X) + p_t(t - t_0) + \langle Z, Y - X \rangle \\ + o\left(\sqrt{\|Y - X\|_{L^2_{\mathbb{P}}}^2 + |t - t_0|^2}\right).$$

## Subdifferentials are plans (J. Marigonda, Quincampoix)

If  $U$  is r.i.,  $(p_t, Z) \in D^- U(t_0, X)$  then:

for all  $(X', Z')$  with  $(X', Z')\#_{\mathbb{P}} = (X, Z)\#_{\mathbb{P}}$  :  $(p_t, Z') \in D^- U(t_0, X')$ .

## Arguing with plans

### $L^2_{\mathbb{P}}$ -Subdifferential = AGS-subdifferential

- $\gamma = (X, Z) \# \mathbb{P}$
- $(p_t, Z) \in D^- U(t_0, X) \Leftrightarrow (p_t, \gamma) \in \partial^-_{\text{AGS}} u(t_0, \mu_0)$ .

### AGS-subdifferential

$(p_t, \gamma) \in \partial^-_{\text{AGS}} u(t_0, \mu_0)$  if:

- For all  $\varpi(x, y, z) \in \mathcal{P}_2(\mathbb{R}^{3d})$  with  $\pi_{x,z} \# \varpi = \gamma$ ,  $\pi_y \# \varpi = \nu$ :

$$u(t, \nu) \geq u(t_0, \mu_0) + p_t(t - t_0) + \int z \cdot (y - x) d\varpi(x, y) \\ + o\left(\sqrt{\|y - x\|_{L^2_{\varpi}}^2 + |t - t_0|^2}\right).$$

## New Hamiltonians

### Extending Hamiltonians using plans (J.)

- Remember  $\mathcal{H}(\mu_0, p)$  is defined for  $\mu_0 \in \mathcal{P}_2(\mathbb{R}^d)$  and  $p \in L^2_{\mu_0}(\mathbb{R}^d, \mathbb{R}^d)$
- Set  $\tilde{\mathcal{H}}((Id, p)\# \mu_0) = \mathcal{H}(\mu_0, p)$ .
- If  $\tilde{\mathcal{H}}$  is uniformly continuous w.r.t.  $W_2$ , we can extend it to all plans:  $\tilde{\mathcal{H}}(\gamma)$ .



## A regular Hamiltonian on $L^2_{\mathbb{P}}$ (J.)

- By construction,  $\tilde{\mathcal{H}}$  is continuous/ $W_2$ .
- By construction, its lift  $\tilde{H}$  is r.i. and continuous/ $L_2$ .
- It is in fact, the only regular extension of  $H$ .

### Turning back to the example

$$\mathcal{H}(\mu, \rho) := \inf_{\underline{u}} \left\{ \int_{\mathbb{R}^d} f(x, \underline{u}(x), \mu) \cdot \rho(x) \, d\mu(x) \right\}$$
$$\tilde{H}(X, Z) = \inf_{\underline{u}} \left\{ \int_{\Omega} f(X, \underline{u}(X, Z), X_{\#}\mathbb{P}) \cdot Z \, d\mathbb{P} \right\}.$$

## Turning back to the example (J.)

$$\tilde{H}(X, Z) = \inf_{\underline{u}} \left\{ \int_{\Omega} f(X, \underline{u}(X, Z), X_{\#}\mathbb{P}) \cdot Z \, d\mathbb{P} \right\}.$$

The function  $V$  is the unique solution in the usual  $L^2_{\mathbb{P}}$ -sense of:

$$\begin{cases} \partial_t U(t, X) + \tilde{H}(X, D_X U(t, X)) = 0, \\ U(T, X) = \mathcal{G}(X_{\#}\mathbb{P}). \end{cases}$$

**Key point:** the dynamic programming principle satisfied by  $\mathcal{V}$  implies a dpp in  $L^2_{\mathbb{P}}$  for  $V$ .

## Other articles in the same spirit

- **Cavagnari, Savaré, Sodini**, *Dissipative probability vector fields and generation of evolution semigroups in Wasserstein spaces*, 2023
- **Bertucci**, *Stochastic optimal transport and Hamilton-Jacobi-Bellman equations on the set of probability measures*, preprint.

The Wasserstein Space  
A multi-agent optimal control problem  
Hamilton-Jacobi in the space of Wasserstein  
Extending the Hamiltonian in  $L^2_{\mathbb{P}}$  in a regular way

# THE END

Thank you for your attention!