

# Inverse Design for scalar conservation laws

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Joint works with Rinaldo Colombo and Abraham Sylla.

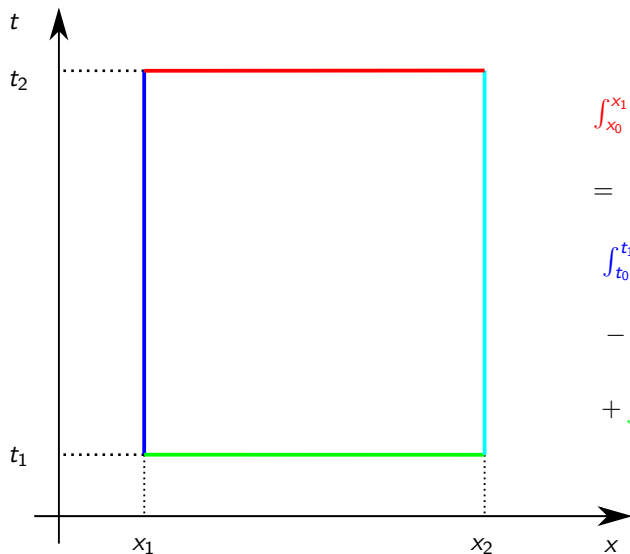
Journées de lancement de l'ANR COSS

# Outline of the talk

- 1 Conservation laws: Origin and Cauchy Problem
  - Origins
  - Regular solutions
  - Entropy solutions
- 2 Inverse Design for Homogeneous Laws: going back in time
- 3 The Non-Homogeneous Case

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# Integral Form



$$\int_{x_0}^{x_1} \rho(t_2, x) dx$$

$$=$$

$$\int_{t_0}^{t_1} F(t, x_1) dx$$

$$- \int_{t_0}^{t_1} F(t, x_2) dx$$

$$+ \int_{x_0}^{x_1} \rho(t_1, x) dx$$

# Differential Form

- Integral Form:  $\rho$  and  $F$  just  $L^1_{loc}$ .
- Differential Form:

$$\rho, F \in \mathcal{C}^1$$

$$\implies \int_{x_1}^{x_2} \int_{t_1}^{t_2} \partial_t \rho(t, x) dt dx = - \int_{t_1}^{t_2} \int_{x_1}^{x_2} \partial_x F(t, x) dt dx$$

$$\implies \frac{\partial \rho}{\partial t}(t, x) + \frac{\partial F}{\partial x}(t, x) = 0.$$

# Closure

- $F(t, x) = -\kappa \partial_x \rho(t, x)$  Heat Equation.

$$\partial_t \rho - \kappa \partial_{xx}^2 \rho = 0.$$

- $F(t, x) = \frac{\rho^2(t, x)}{2}$  Burgers' equation (inspired by Euler's equation)

$$\partial_t \rho + \partial_x \left( \frac{\rho^2}{2} \right) = 0$$

- $F(t, x) = \rho(t, x) v_{\max} \left( 1 - \frac{\rho(t, x)}{\rho_{\max}} \right)$  LWR equation

$$\partial_t \rho + \partial_x \left( \rho(t, x) v_{\max} \left( 1 - \frac{\rho(t, x)}{\rho_{\max}} \right) \right) = 0$$

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# Characteristics' method

$$\bullet \begin{cases} \partial_t \rho + \partial_x f(\rho) = 0 \\ \rho(0, x) = \rho_0(x) \\ \rho \in \mathcal{C}^1 \end{cases}$$

$$\bullet \partial_t \rho + \partial_x f(\rho) = 0$$

$$\implies \partial_t \rho + f'(\rho) \partial_x \rho = 0,$$

$$\bullet \begin{cases} q \in \mathcal{C}^1(\mathbb{R}^+; \mathbb{R}) \\ p(t) := \rho(t, q(t)) \end{cases}$$

$$\implies \dot{p}(t) = \partial_t \rho + \dot{q}(t) \partial_x \rho,$$

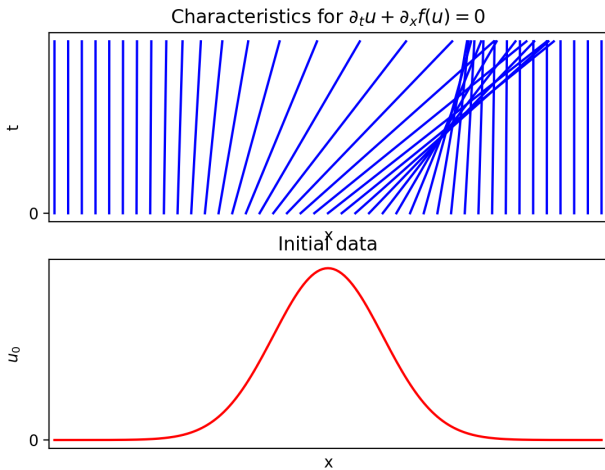
$$" \implies " \begin{cases} \dot{q}(t) = f'(\rho(t)) \\ \dot{p}(t) = 0 \end{cases}$$

$$\implies \begin{cases} p(t) = p(0) \\ \dot{q}(t) = f'(\rho(0)) \end{cases}$$

$$\implies \rho(t, x) = \rho_0(x - tf'(\rho(t, x)))$$

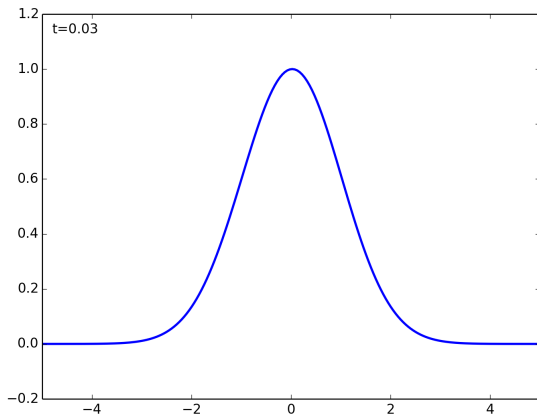


# In a picture with Burgers $f'(q) = q$



# Animated

- Let the plane evolve according to  $\dot{p} = 0$  and  $\dot{q} = f'(p)$ .
- Look at the evolution of the graph of  $p = \rho(t, q)$ .



# Generic Blowup

$$\begin{cases} \partial_t \rho + \partial_x f(\rho) = 0, & t > 0, \quad x \in \mathbb{R}, \\ \rho(0, x) = \rho_0(x). \end{cases} \quad (1)$$

## Theorem

For  $f(\rho) = \frac{\rho^2}{2}$  (in fact convex or concave) and any  $\rho_0 \in C_c^\infty(\mathbb{R})$

$$\rho_0 \not\equiv 0 \Rightarrow \exists T > 0, \quad \exists X \in \mathbb{R}, \quad \partial_x \rho(t, X) \xrightarrow{t \rightarrow T^-} -\infty.$$

But

$$\|\rho(t, \cdot)\|_{L^\infty(\mathbb{R})} \leq \|\rho_0\|_{L^\infty(\mathbb{R})}.$$

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# Weak/Integral solutions

Three formulations, different regularity.

- Differential:  $\partial_t \rho(t, x) + \partial_x f(\rho(t, x)) = 0,$   
 $\forall t > 0, \forall x \in \mathbb{R}$
- Integral:  $\frac{d}{dt} \int_a^b \rho(t, x) dx = f(\rho(t, a)) - f(\rho(t, b))$   
 $\forall t > 0, \quad \forall a < b$
- Weak:  $\int_0^{+\infty} \int_{-\infty}^{+\infty} \rho(t, x) \partial_t \phi(t, x) + f(\rho(t, x)) \partial_x \phi(t, x) dx dt = 0$   
 $\forall \phi \in \mathcal{C}_c^\infty((0, +\infty) \times \mathbb{R}).$

# Vanishing Viscosity and entropy solution.

- Analogy with gas dynamics

$$\partial_t \rho^\epsilon + \partial_x f(\rho^\epsilon) = \epsilon \partial_{xx}^2 \rho^\epsilon. \quad (2)$$

- For  $E$  convex,  $Q' = E' f'$ .

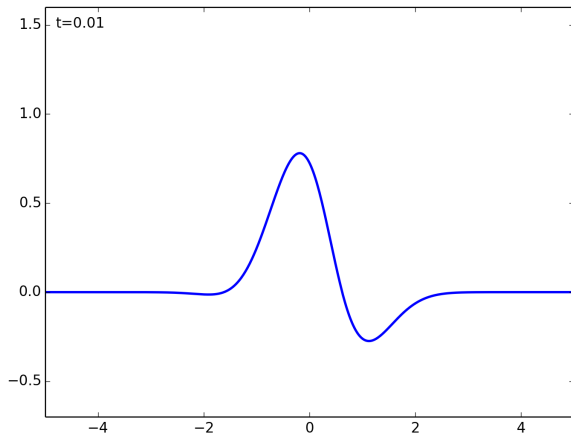
$$\partial_t E(\rho) + \partial_x Q(\rho) = \epsilon \partial_{xx}^2 E(\rho) - E''(\rho) (\partial_x \rho)^2.$$

- $\epsilon \rightarrow 0^+$  (**FORMALLY**):

$$\partial_t E(\rho) + \partial_x Q(\rho) \leq 0, \quad \mathcal{D}((0, +\infty) \times \mathbb{R})$$

- $\rho = (t, x) \mapsto (S_t \rho_0)(x)$ ,  $(S_t)_{t \geq 0}$  semigroup of entropy solutions.

# Simulations



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# What and Why!

Questions:

- ① What is  $S_t(L^\infty(\mathbb{R}))$ ?
- ② Characterize  $I_T(\omega) := \{\rho_0 \in L^\infty(\mathbb{R}) : S_T \rho_0 = \omega\}$  for  $\omega \in L^\infty(\mathbb{R})$ ?

Reasons:

- ① Irreversible dynamics for entropy solutions.
- ② Entropy semigroup compactifying.
- ③ Sonic boom minimization. (Gosse-Zuazua 17)
- ④ Accident localization through tollgate estimates.
- ⑤ Control theory through Russell's extension method (Ancona-Marson 98, Horsin 98, ...).

# Characterization of reachable states

Going back to Oleinik 56!

## Definition

$$T > 0, \quad \omega \in L^\infty(\mathbb{R}) \quad r_\omega^T(x) := x - Tf'(\omega(x)).$$

## Theorem

For  $f$  convex,

$$I_T(\omega) \neq \emptyset \iff \omega \in S_T(L^\infty(\mathbb{R})) \iff r_\omega^T \text{ nondecreasing a.e.}$$

- ①  $\omega \in S_T(L^\infty(\mathbb{R})) \implies \omega \in \text{BV}(\mathbb{R})$ ,
- ② Not better: take  $r_\omega^T$  Cantor's staircase.

# Characterization of initial data

Theorem (Colombo-P. 2020)

$I_T(\omega) \neq \emptyset \implies$

- ①  $I_T(\omega)$  convex,
- ②  $I_T(\omega)$  is a cone of vertex  $\rho_0^*$ ,
- ③  $I_T(\omega)$  is a  $F_\sigma$  set for the  $L^1_{loc}$  topology.

Furthermore

- ①  $I_T(\omega)$  singleton iff additionally  $\omega \in \mathcal{C}^0$
- ② otherwise unbounded  $L^\infty$ , but locally  $L^\infty$  closed  $L^1_{loc}$ ,
- ③ and there is no extremal facet of finite dimension besides  $\rho_0^*$

In fact complete characterization of  $I_T(\omega)$ .

$\rho_0^*$ : reversing space and time

①  $\omega, T$  such that  $r_\omega^T$  increasing

②  $\chi$  solution of

$$\begin{cases} \partial_s \chi + \partial_y f(\chi) = 0, \\ \chi(0, y) = \omega(-y) \end{cases}$$

③  $\chi$  isentropic:  $\partial_s E(\chi) + \partial_y Q(\chi) = 0$  (in fact “regular”)

④  $\rho(t, x) := \chi(T - t, -x)$  entropy solution

$$\partial_t \rho + \partial_x f(\rho) = 0.$$

⑤  $\rho_0^* := \rho(0) \in I_T(\omega)$

# Tool: the Hopf-Lax formula

$$\begin{cases} \partial_t \rho + \partial_x (f(\rho)) = 0 \\ \rho(0) = \rho_0 \end{cases}$$

$f$  strongly convex  $\iff f^*$  Legendre transform

$$\begin{cases} r(t, x) := \arg \min_{y \in \mathbb{R}} \left( t f^* \left( \frac{x-y}{t} \right) + \int_0^y \rho_0(z) dz \right) \\ \rho(t, x) = f' \left( \frac{x-r(t,x)}{t} \right) \end{cases}$$

AND

enough minimizers depending only on  $\omega$ !



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# Why?

- ① LWR: different speed limit, different number of lanes:

$$\partial_t \rho(t, x) + \partial_x \left( \rho(t, x) v_{\max}(x) \left( 1 - \frac{\rho(t, x)}{\rho_{\max}(x)} \right) \right) = 0.$$

- ② Nonhomogeneous conservation laws:

- ① Richer geometry!
- ②  Litterature 

- ③ Homogeneity in space too special:

- ① Vanishing viscosity for LWR?
- ② Infinitely many contracting semigroups of weak solutions!

# Characteristics equation

$$\bullet \begin{cases} \partial_t \rho + \partial_x (H(x, \rho)) = 0 \\ \rho(0, x) = \rho_0(x) \\ \rho \in \mathcal{C}^1 \end{cases}$$

$$\bullet \partial_t \rho + \partial_x (H(x, \rho)) = 0$$

$$\implies \partial_t \rho + \partial_2 H(x, \rho) \partial_x \rho = -\partial_1 H(x, \rho),$$

$$\bullet \begin{cases} q \in \mathcal{C}^1(\mathbb{R}^+; \mathbb{R}) \\ \rho(t) := \rho(t, q(t)) \end{cases}$$

$$\implies \dot{\rho}(t) = \partial_t \rho + \dot{q}(t) \partial_x \rho,$$

$$\text{"} \implies \text{"} \begin{cases} \dot{q}(t) = \partial_2 H(q(t), \rho(t)) \\ \dot{\rho}(t) = -\partial_1 H(q(t), \rho(t)) \end{cases}$$



# Inverse design results: The Same?

$$T > 0, \omega \in L^\infty(\mathbb{R}), \quad r_\omega^T(x) := q(0) \text{ where } \begin{cases} \dot{q}(t) = \partial_2 H(q(t), p(t)) \\ \dot{p}(t) = -\partial_1 H(q(t), p(t)) \\ q(T) = x, \quad p(T) = w(x). \end{cases}$$

## Theorem (Colombo-P.-Sylla)

When  $\forall x, \quad q \mapsto H(x, q)$  strongly convex

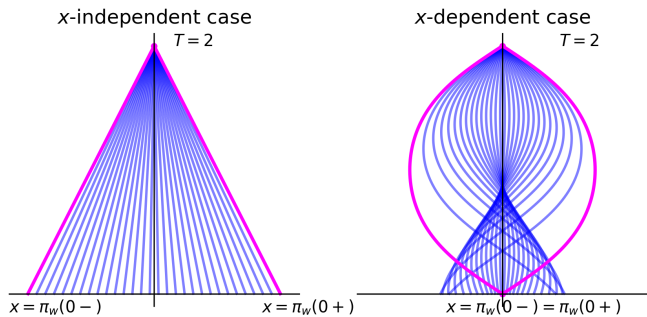
$$I_T(\omega) \neq \emptyset \iff \omega \in S_T(L^\infty(\mathbb{R})) \iff r_\omega^T \text{ nondecreasing a.e. } \triangle!$$

And  $I_T(\omega) \neq \emptyset \implies$

- ①  $I_T(\omega)$  convex,
- ②  $I_T(\omega)$  is a cone,
- ③  $I_T(\omega)$  is a  $F_\sigma$  set for the  $L_{loc}^1$  topology.

...

## Oops



# Inverse design results: but not exactly

## Theorem (Colombo-P.-Sylla)

There exists,  $T > 0$ ,  $H$  and  $\omega$  such that

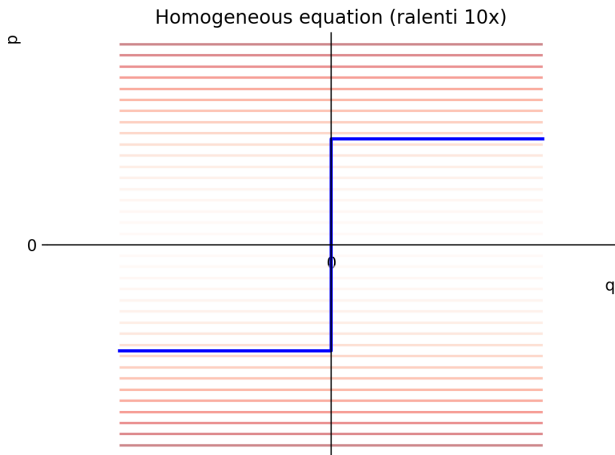
- ①  $I_T(\omega) \neq \emptyset$ ,
- ②  $\forall \rho_0 \in I_T(\omega), \exists (E, Q)$  entropy-entropy flux pair, such that

$$\partial_t E(\rho) + \partial_x (Q(x, \rho)) - E'(\rho) \partial_1 H(x, \rho) - \partial_1 Q(x, \rho) \neq 0$$

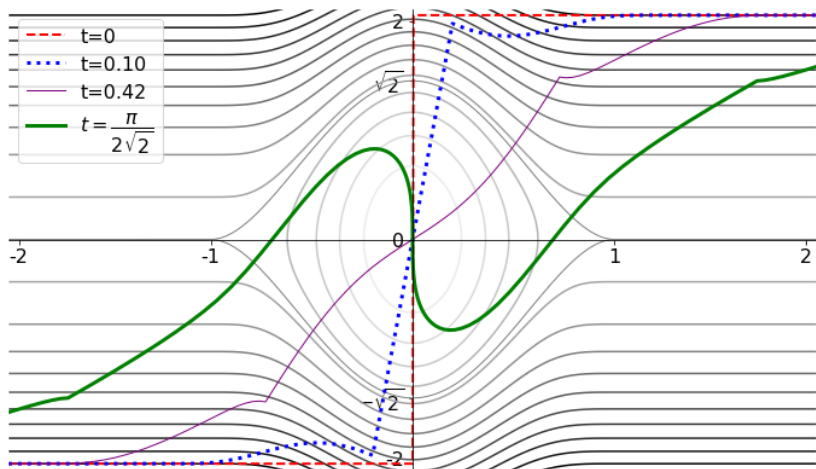
## Remark

- ① *Isentropic solutions “=” closure of classical solutions.*
- ② *Range of  $S_t$  homogeneous: just look at classical solutions.*
- ③ *Range of  $S_t$  nonhomogeneous: larger.*

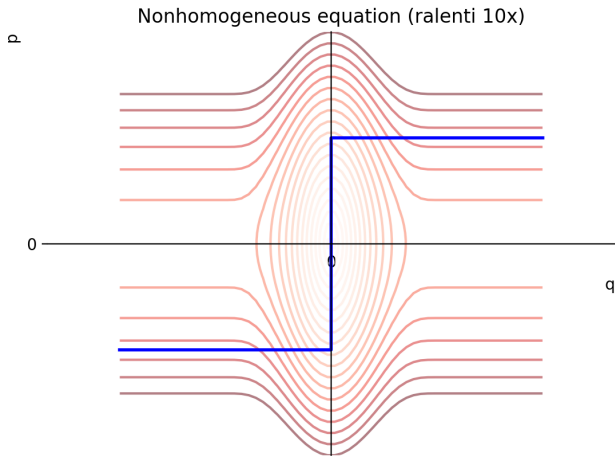
# Rarefaction in the homogeneous case



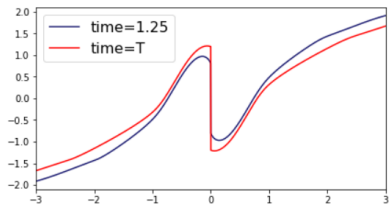
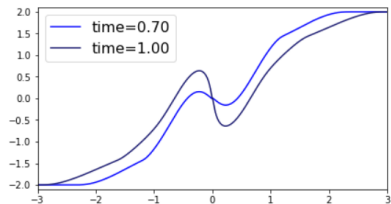
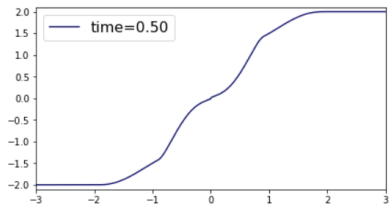
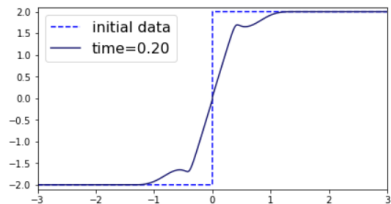
# Hamiltonian Flow



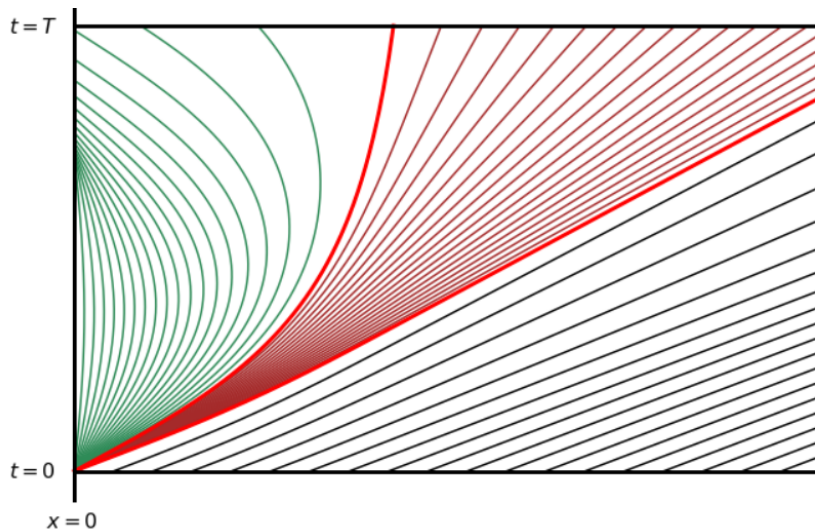
# Rarefaction in the nonhomogeneous case



# Solution of the PDE



# The forward characteristics





# Tool: Hamilton-Jacobi connection and optimal control

If  $L(x, q) = \sup_{p \in \mathbb{R}} (pq - H(x, p))$  (Legendre transform)

$$\begin{cases} V(t, x) := \inf_{c \in L^\infty(0, T)} \left( \int_0^t L(y(s), c(s)) ds + P(y(0)) \right) \\ \dot{y}(s) = c(s) \quad 0 < s < t \\ y(t) = x \end{cases}$$

$$\iff \begin{cases} \partial_t V + H(x, \partial_x V) = 0, \\ V(0) = P \\ V \text{ viscosity solution} \end{cases}$$

$$\stackrel{\rho = \partial_x V}{\iff} \begin{cases} \partial_t \rho + \partial_x (H(x, \rho)) = 0, \\ \rho(0) = P' \\ \rho \text{ entropy solution} \end{cases}$$

# Open Problems

- Numerics.
- Nonconvex Flux.
  - ① Generic flux: no more convexity of  $I_T$ !
  - ② Still HJB but differential games, Isaacs condition?
- Multi dimensional conservation laws.
  - ① No more HJB!
  - ② Still entropy measure.
- Systems of conservation laws.

# References

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